

NEW



DC-Gearmotors

with optical Encoder
flat ironless rotor

100 mNm

For combination with
Drive Electronics:
SC 1801 (Speed Controller)

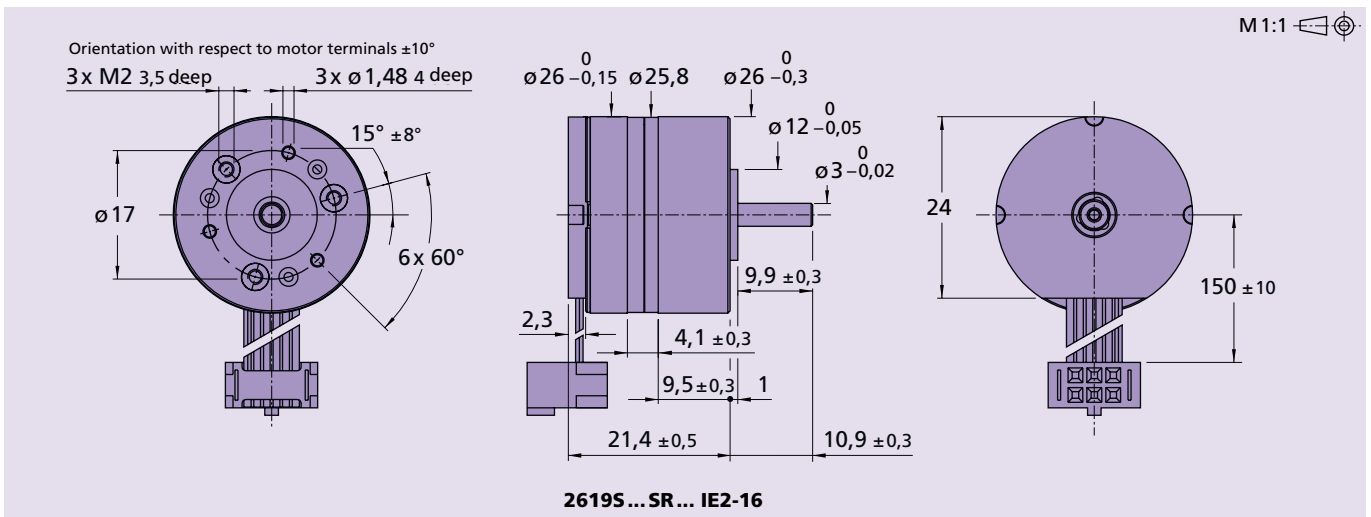
Series 2619 ... SR ... IE2-16

	2619 S	003 SR IE2	006 SR IE2	012 SR IE2	024 SR IE2	
Nominal voltage	U _N	3	6	12	24	Volt
Terminal resistance	R	1,68	7,9	30,8	115	Ω
Output power	P _{2 max.}	1,31	1,11	1,14	1,22	W
No-load speed (motor)	n ₀	7 200	6 700	6 900	7 200	rpm
Speed constant	k _n	2 430	1 130	582	304	rpm/V
Back-EMF constant	k _E	0,412	0,884	1,72	3,29	mV/rpm
Torque constant	k _M	3,93	8,44	16,4	31,4	mNm/A
Current constant	k _I	0,254	0,118	0,061	0,032	A/mNm
Slope of n-M curve	Δn/ΔM	1 040	1 060	1 090	1 110	rpm/mNm
Rotor inductance	L	90	420	1 600	5 800	μH
Rotor inertia	J	0,68	0,68	0,68	0,68	gcm ²

Housing material		plastic				
Geartrain material		metal				
Backlash, at no-load	≤	4				°
Bearings on output shaft		brass / ceramic bearings	ball bearings			
Shaft load max.:		(standard)	(optional)			N
– radial (3 mm from bearing)	≤	5	15			N
– axial	≤	2	5			N
Shaft press fit force, max.	≤	10	10			N
Shaft play:						
– radial (5 mm from mounting face)	≤	0,07	0,03			mm
– axial	≤	0,25	0,25			mm
Operating temperature range		– 30 ... + 80				°C

Specifications

reduction ratio (rounded)	output speed up to n _{max} rpm	weight with motor g	output torque		direction of rotation (reversible)	efficiency %
			continuous operation M _{max} mNm	intermittent operation M _{max} mNm		
8 : 1	635	25	9	30	=	81
22 : 1	223	26	23	75	≠	73
33 : 1	151	26	30	100	=	60
112 : 1	44	27	93	180	≠	59
207 : 1	24	27	100	180	=	53
361 : 1	14	27	100	180	=	53
814 : 1	6	28	100	180	=	43
1 257 : 1	4	29	100	180	=	43



Integrated optical Encoder	2619 ... SR	IE2-16	
Lines per revolution	N	16	
Signal output, square wave		2	channels
Supply voltage	U _{DD}	3,2 ... 5,5	V DC
Current consumption, typical (U _{DD} = 5V DC)	I _{DD}	typ. 8, max. 15	mA
Output current, max. allowable (at U _{out} < 1,5V)	I _{OUT}	5	mA
Pulse width ¹⁾	P	180 ± 45	°e
Phase shift, channel A to B ¹⁾	Φ	90 ± 45	°e
Signal rise/fall time, max. (C _{LOAD} = 50 pF)	tr/tf	2,5/0,3	µs
Frequency range ²⁾ , up to	f	4,5	kHz
Operating temperature range		0 ... +70	°C

¹⁾ Ambient temperature 22°C (tested at 1kHz)

²⁾ Velocity (rpm) = f(Hz) x 60/N

Features

In this version, the DC-Micromotors have an optical encoder with two output channels. A code wheel on the shaft is optically captured and further processed. At the encoder outputs, two 90° phase-shifted rectangular signals are available with 16 impulses per motor revolution.

The encoder is suitable for the monitoring and regulation of the speed and direction of rotation and for positioning the drive shaft.

The supply voltage for the encoder and the DC-Micromotor as well as the two channel output signals are interfaced through a ribbon cable with connector.

Order information

■ Ordering examples:

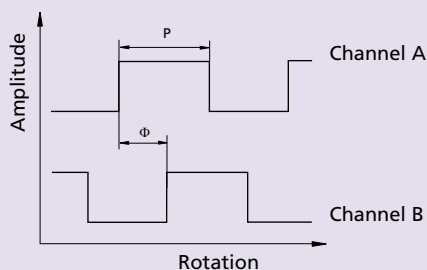
2619S003SR 8:1 IE2-16

2619S024SR 1257:1 IE2-16

Output signals / Circuit diagram / Connector information

Output signals

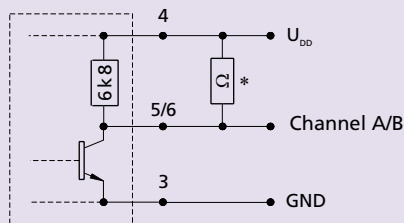
with clockwise rotation as seen from the shaft end



Admissible deviation of phase shift:

$$\Delta\Phi = \left| 90^\circ - \frac{\Phi}{P} * 180^\circ \right| \leq 45^\circ$$

Output circuit



* An additional external pull-up resistor can be added to improve the rise time. Caution: I_{OUT} max. 5 mA must not be exceeded!

