

Optical Encoders

Features:

50 Lines per revolution 2 Channels Digital output

PA2-50

Signal output, square wave		2	channels
Supply voltage (ripple < 100 mV _{p-p})	V_{cc}	2,7 3,3	V DC
Current consumption, typical ($V_{CC} = 3 \text{ V DC}$)	I cc	8,5	mA
Current output, per channel	I out	- 1 8	mA
Pulse width	P	180 ± 50	°e
Phase shift, channel A to B	Φ	90 ± 45	°e
Logic state width	S	90 ± 50	°e
Cycle	C	360 ± 36	°e
Signal rise/fall time, typical ($C_{LOAD} = 25 pF$)	tr/tf	0,3 / 0,1	μs
Rotational speed up to	n _{max} .	24 000	rpm
Inertia of code disc	J	0,02	gcm ²
Operating temperature range		– 30 + 85	°C

Ordering information				
Encoder	number of channels	lines per revolution	for combination with: DC-Micromotors series	
PA2-50	2	50	0615 S	

Note: Lines per revolution refers to pre-quadrature resolution and equals the cycles per revolution

Features

These incremental shaft encoders in combination with the DC-Micromotors and Brushless DC-Servomotors are designed for both indication and control of both shaft velocity and direction of rotation as well as for positioning.

An all-in-one emitter and detector chip (AEDR 8400) transmits and receives LED light reflected off a low inertia reflective disc providing two channels with 90° phase shift.

The supply voltage for the encoder and the DC-Micromotor and Brushless DC-Servomotor as well as the output signals are interfaced with a flexible printed circuit (FPC) for connection to a 6-pin 0,5 mm pitch Molex ZIF connector.

Details for the DC-Micromotors and Brushless DC-Servomotors and suitable reduction gearheads are on separate catalog pages.

Connection

Output signals / Circuit diagram / Connector information



